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► To cite this version:

Florent Malrieu. Some simple but challenging Markov processes. Annales de la Faculté des Sciences de Toulouse. Mathématiques., 2015, 24 (4), pp.857-883. 10.5802/afst.1468 . hal-01097576

HAL Id: hal-01097576

<https://hal.science/hal-01097576>

Submitted on 19 Dec 2014

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Some simple but challenging Markov processes

Florent Malrieu

December 19, 2014

Abstract

In this note, we present few examples of Piecewise Deterministic Markov Processes and their long time behavior. They share two important features: they are related to concrete models (in biology, networks, chemistry, ...) and they are mathematically rich. Their mathematical study relies on coupling method, spectral decomposition, PDE technics, functional inequalities. We also relate these simple examples to recent and open problems.

1 Introduction

A Piecewise deterministic Markov processes (PDMP¹) is a stochastic process involving deterministic motion punctuated by random jumps. This large class of non diffusion stochastic models was introduced in the literature by Davis [20, 21] (see also [34]). As it will be stressed below, these processes arise naturally in many application areas: biology, communication networks, reliability of complex systems for example. From a mathematical point of view, they are simple to define but their study may require a broad spectrum of tools as stochastic coupling, functional inequalities, spectral analysis, dynamical systems, partial differential equations.

The aim of the present paper is to present simple examples of PDMP appearing in different applied frameworks and to investigate their long time behavior. Rather than using generic technics (as Meyn-Tweedie-Foster-Lyapunov... strategy) we will focus on as explicit as possible estimates. Several open and motivating questions (stability criteria, regularity of the invariant measure(s), explicit rate of convergence...) are also listed along the paper.

Roughly speaking the dynamics of a PDMP on a set E depends on three local characteristics, namely, a flow φ , a jump rate λ and a transition kernel Q . Starting from x , the motion of the process follows the flow $t \mapsto \varphi_t(x)$ until the first jump time T_1 which occurs in a Poisson-like fashion with rate $\lambda(x)$. More precisely, the distribution of the first jump time is given by

$$\mathbb{P}_x(T_1 > t) = \exp\left(-\int_0^t \lambda(\varphi_s(x)) ds\right).$$

Then, the location of the process at the jump time T_1 is selected by the transition measure $Q(\varphi_{T_1}(x), \cdot)$ and the motion restarts from this new point as before. This motion is summed up by the infinitesimal generator:

$$Lf(x) = F(x) \cdot \nabla f(x) + \lambda(x) \int_E (f(y) - f(x)) Q(x, dy), \quad (1)$$

where F is the vector field associated to the flow φ . In several examples, the process may jump when it hits the boundary of E . The boundary of the space ∂E can be seen as a region where the jump rate is infinite (see for example [18] for the study of billiards in a general domain with random reflections).

¹This may also mean "Persi Diaconis: Mathemagician and Popularizer".

In the sequel, we denote by $\mathcal{P}(\mathbb{R}^d)$ the set of probability measures on $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d))$ and, for any $p \geq 1$, by $\mathcal{P}_p(\mathbb{R}^d)$ the set of probability measures on $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d))$ with a finite p^{th} -moment: $\mu \in \mathcal{P}_p(\mathbb{R}^d)$ if

$$\int_{\mathbb{R}^d} |x|^p \mu(dx) < +\infty.$$

The total variation distance on $\mathcal{P}(\mathbb{R}^d)$ is given by

$$\begin{aligned} \|\nu - \tilde{\nu}\|_{\text{TV}} &= \inf \left\{ \mathbb{P}(X \neq \tilde{X}) : X \sim \nu, \tilde{X} \sim \tilde{\nu} \right\} \\ &= \sup \left\{ \int f d\nu - \int f d\tilde{\nu} : f \text{ bounded by } 1/2 \right\}. \end{aligned}$$

If ν and $\tilde{\nu}$ are absolutely continuous with respect to μ with density functions g and \tilde{g} , then

$$\|\nu - \tilde{\nu}\|_{\text{TV}} = \frac{1}{2} \int_{\mathbb{R}^d} |g - \tilde{g}| d\mu.$$

For $p \geq 1$, the Wasserstein distance of order p , defined on $\mathcal{P}_p(\mathbb{R}^d)$, is given by

$$W_p(\nu, \tilde{\nu}) = \inf \left\{ \left[\mathbb{E}(|X - \tilde{X}|^p) \right]^{1/p} : X \sim \nu, \tilde{X} \sim \tilde{\nu} \right\}.$$

Similarly to the total variation distance, the Wasserstein distance of order 1 has a nice dual formulation:

$$W_1(\nu, \tilde{\nu}) = \sup \left\{ \int f d\nu - \int f d\tilde{\nu} : f \text{ is 1-Lipschitz} \right\}.$$

A generic dual expression can be formulated for W_p (see [62]).

2 Storage models, with a bandit...

Let us consider the PDMP driven by the following infinitesimal generator:

$$Lf(x) = -\beta x f'(x) + \alpha \int_0^\infty (f(x+y) - f(x)) e^{-y} dy.$$

Such processes appear in the modeling of storage problems or pharmacokinetics that describe the evolution of the concentration of a chemical product in the human body. The present example is studied in [59, 6]. More realistic models are studied in [11, 14]. Similar processes can also be used as stochastic gene expression models (see [42, 65]).

In words, the current stock X_t decreases exponentially at rate β , and increases at random exponential times by a random (exponentially distributed) amount. Let us introduce a Poisson process $(N_t)_{t \geq 0}$ with intensity α and jump times $(T_i)_{i \geq 0}$ (with $T_0 = 0$) and a sequence $(E_i)_{i \geq 1}$ of independent random variables with an exponential law of parameter 1 independent of $(N_t)_{t \geq 0}$. The process $(X_t)_{t \geq 0}$ starting from $x \geq 0$ can be constructed as follows: for any $i \geq 0$,

$$X_t = \begin{cases} e^{-\beta(t-T_i)} X_{T_i} & \text{if } T_i \leq t < T_{i+1}, \\ e^{-\beta(T_{i+1}-T_i)} X_{T_i} + E_{i+1} & \text{if } t = T_{i+1}. \end{cases}$$

This model is sufficiently naïve to express the Laplace transform of X .

Lemma 2.1 (Laplace transform). *For any $t \geq 0$ and $s < 1$, the Laplace transform of X_t is given by*

$$L(t, s) := \mathbb{E}(e^{sX_t}) = L(0, se^{-\beta t}) \left(\frac{1 - se^{-\beta t}}{1 - s} \right)^{\alpha/\beta},$$

where $L(0, \cdot)$ stands for the Laplace transform of X_0 . In particular, the invariant distribution of X is the Gamma distribution with density

$$x \mapsto \frac{x^{\alpha/\beta-1} e^{-x}}{\Gamma(\alpha/\beta)} \mathbb{1}_{[0,+\infty)}(x).$$

Proof. Applying the infinitesimal generator to $x \mapsto e^{sx}$, one deduces that the function L is solution of the following partial differential equation:

$$\partial_t L(t, s) = -\beta s \partial_s L(t, s) + \frac{\alpha s}{1-s} L(t, s).$$

More generally, if the random income is non longer exponentially distributed but has a Laplace transform L_i then L is solution of

$$\partial_t L(t, s) = -\beta s \partial_s L(t, s) + \alpha(L_i(s) - 1)L(t, s).$$

As a consequence, if G is given by $G(t, s) = \log L(t, s) + (\alpha/\beta) \log(1-s)$ then

$$\partial_t G(t, s) = -\beta s \partial_s G(t, s).$$

The solution of this partial differential equation is given by $G(t, s) = G(0, se^{-\beta t})$. □

The next step is to investigate the convergence to equilibrium.

Theorem 2.2 (Convergence to equilibrium). *Let us denote by νP_t the law of X_t if X_0 is distributed according to ν . For any $x, y \geq 0$ and $t \geq 0$ and $p \geq 1$,*

$$W_p(\delta_x P_t, \delta_y P_t) \leq |x - y| e^{-\beta t},$$

and (when $\alpha \neq \beta$)

$$\|\delta_x P_t - \delta_y P_t\|_{\text{TV}} \leq e^{-\alpha t} + |x - y| \alpha \frac{e^{-\beta t} - e^{-\alpha t}}{\alpha - \beta}. \quad (2)$$

Moreover, if μ is the invariant measure of the process X , we have for any probability measure ν with a finite first moment and $t \geq 0$,

$$\|\nu P_t - \mu\|_{\text{TV}} \leq \|\nu - \mu\|_{\text{TV}} e^{-\alpha t} + W_1(\nu, \mu) \alpha \frac{e^{-\beta t} - e^{-\alpha t}}{\alpha - \beta}.$$

Remark 2.3 (Limit case). *In the case $\alpha = \beta$, the upper bound (2) becomes*

$$\|\delta_x P_t - \delta_y P_t\|_{\text{TV}} \leq (1 + |x - y| \alpha t) e^{-\alpha t}.$$

Remark 2.4 (Optimality). *Applying L to the test function $f(x) = x^n$ allows us to compute recursively the moments of X_t . In particular,*

$$\mathbb{E}_x(X_t) = \frac{\alpha}{\beta} + \left(x - \frac{\alpha}{\beta}\right) e^{-\beta t}.$$

This relation ensures that the rate of convergence for the Wasserstein distance is sharp. Moreover, the coupling for the total variation distance requires at least one jump. As a consequence, the exponential rate of convergence is greater than α . Thus, Equation (2) provides the optimal rate of convergence $\alpha \wedge \beta$.

Proof of Theorem 2.2. Firstly, consider two processes X and Y starting respectively at x and y and driven by the same randomness (*i.e.* Poisson process and jumps). Then the distance between X_t and Y_t is deterministic:

$$X_t - Y_t = (x - y)e^{-\beta t}.$$

Obviously, for any $p \geq 1$ and $t \geq 0$,

$$W_p(\delta_x P_t, \delta_y P_t) \leq |x - y|e^{-\beta t}.$$

Let us now construct explicitly a coupling at time t to get the upper bound (2) for the total variation distance. The jump times of $(X_t)_{t \geq 0}$ and $(Y_t)_{t \geq 0}$ are the ones of a Poisson process $(N_t)_{t \geq 0}$ with intensity α and jump times $(T_i)_{i \geq 0}$. Let us now construct the jump heights $(E_i^X)_{1 \leq i \leq N_t}$ and $(E_i^Y)_{1 \leq i \leq N_t}$ of X and Y until time t . If $N_t = 0$, no jump occurs. If $N_t \geq 1$, we choose $E_i^X = E_i^Y$ for $1 \leq i \leq N_t - 1$ and $E_{N_t}^X$ and $E_{N_t}^Y$ in order to maximise the probability

$$\mathbb{P}\left(X_{T_{N_t}} + E_{N_t}^X = Y_{T_{N_t}} + E_{N_t}^Y \mid X_{T_{N_t}}, Y_{T_{N_t}}\right).$$

This maximal probability of coupling is equal to

$$\exp\left(-|X_{T_{N_t}} - Y_{T_{N_t}}|\right) = \exp\left(-|x - y|e^{-\beta T_{N_t}}\right) \geq 1 - |x - y|e^{-\beta T_{N_t}}.$$

As a consequence, we get that

$$\begin{aligned} \|\delta_x P_t - \delta_y P_t\|_{\text{TV}} &\leq 1 - \mathbb{E}\left[\left(1 - |x - y|e^{-\beta T_{N_t}}\right)\mathbb{1}_{\{N_t \geq 1\}}\right] \\ &\leq e^{-\alpha t} + |x - y|\mathbb{E}\left(e^{-\beta T_{N_t}}\mathbb{1}_{\{N_t \geq 1\}}\right). \end{aligned}$$

The law of T_n conditionally on the event $\{N_t = n\}$ has the density

$$u \mapsto n \frac{u^{n-1}}{t^n} \mathbb{1}_{[0, t]}(u).$$

This ensures that

$$\mathbb{E}\left(e^{-\beta T_{N_t}} \mathbb{1}_{\{N_t \geq 1\}}\right) = \int_0^1 e^{-\beta t v} \mathbb{E}\left(N_t v^{N_t-1}\right) dv.$$

Since the law of N_t is the Poisson distribution with parameter αt , one has

$$\mathbb{E}\left(N_t v^{N_t-1}\right) = \alpha t e^{\alpha t(v-1)}.$$

This ensures that

$$\mathbb{E}\left(e^{-\beta T_{N_t}} \mathbb{1}_{\{N_t \geq 1\}}\right) = \alpha \frac{e^{-\beta t} - e^{-\alpha t}}{\alpha - \beta},$$

which completes the proof. Finally, to get the last estimate, we proceed as follows: if N_t is equal to 0, a coupling in total variation of the initial measures is done, otherwise, we use the coupling above. \square

Remark 2.5 (Another example). *Surprisingly, a process of the same type appears in [37] in the study of the so-called bandit algorithm. The authors have to investigate the long time behavior of the process driven by*

$$Lf(y) = (1 - p - py)f'(y) + qy \frac{f(y + g) - f(y)}{g},$$

where $0 < q < p < 1$ and $g > 0$. This can be done following the lines of the proof of Theorem 2.2.

3 The TCP model with constant jump rate

This section is devoted to the process on $[0, +\infty)$ driven by the following infinitesimal generator

$$Lf(x) = f'(x) + \lambda(f(x/2) - f(x)) \quad (x \geq 0).$$

In other words, the process grows linearly between jump times that are the one of a homogeneous Poisson process with parameter λ and it is divided by 2 at these instants of time. See Section 3.4 for concrete motivations and generalizations.

3.1 Spectral decomposition

Without loss of generality, we choose $\lambda = 1$ in this section. The generator L of the naïve TCP process preserves the degree of polynomials. As a consequence, for any $n \in \mathbb{N}$, the eigenvalue $\lambda_n = -(1 - 2^{-n})$ is associated to a polynomials P_n with degree n . As an example,

$$P_0(x) = 1, \quad P_1(x) = x - 2 \quad \text{and} \quad P_2(x) = x^2 - 8x + 32/3.$$

Moreover, one can explicitly compute the moments of the invariant measure μ (see [39]): for any $n \in \mathbb{N}$

$$\int x^n \mu(dx) = \frac{n!}{\prod_{k=1}^n (1 - 2^{-k})}.$$

Roughly speaking, this relation comes from the fact that the functions $m_n : t \in [0, \infty) \mapsto \mathbb{E}(X_t^n)$ for $n \geq 0$ are solution of

$$m'_n(t) = nm_{n-1}(t) + (2^{-n} - 1)m_n(t).$$

It is also shown in [24] that the Laplace transform of μ is finite on a neighborhood of the origin. As a consequence, the polynomials are dense in $L^2(\mu)$. Unfortunately, the eigenvectors of L are not orthogonal in $L^2(\mu)$. For example,

$$\int P_1 P_2 d\mu = -\frac{64}{27}.$$

This lack of symmetry (due to the fact that the invariant measure μ is not reversible) prevents us to easily deduce an exponential convergence to equilibrium in L^2_μ .

When the invariant measure is reversible, the spectral decomposition (and particularly its spectral gap) of L provides fine estimates for the convergence to equilibrium. See for example [41] and the connection with coupling strategies and strong stationary times introduced in [1].

Open question 1 (Spectral proof of ergodicity). *Despite the lack of reversibility, is it possible to use the spectral properties of L to get some estimates on the long time behavior of X ?*

Remark 3.1. *This spectral approach has been fruitfully used in [28, 45] to study (nonreversible) hypocoercive models.*

3.2 Convergence in Wasserstein distances

The convergence in Wasserstein distance is obvious.

Lemma 3.2 (Convergence in Wasserstein distance [57, 16]). *For any $p \geq 1$,*

$$W_p(\delta_x P_t, \delta_y P_t) \leq |x - y| e^{-\lambda_p t} \quad \text{with} \quad \lambda_p = \frac{\lambda(1 - 2^{-p})}{p}. \quad (3)$$

Remark 3.3 (Alternative approach). *The case $p = 1$ is obtained in [57] by PDEs estimates using the following alternative formulation of the Wasserstein distance on \mathbb{R} . If the cumulative distribution functions of the two probability measures ν and $\tilde{\nu}$ are F and \tilde{F} then*

$$W_1(\nu, \tilde{\nu}) = \int_{\mathbb{R}} |F(x) - \tilde{F}(x)| dx.$$

The general case $p \geq 1$ is obvious from the probabilistic point of view: choosing the same Poisson process $(N_t)_{t \geq 0}$ to drive the two processes provides that the two coordinates jump simultaneously and

$$|X_t - Y_t| = |x - y|2^{-N_t}.$$

As a consequence, since the law of N_t is the Poisson distribution with parameter λt , one has

$$\mathbb{E}_{x,y}(|X_t - Y_t|^p) = |x - y|^p \mathbb{E}(2^{-pN_t}) = |x - y|^p e^{-p\lambda_p t}.$$

This coupling turns out to be sharp. Indeed, one can compute explicitly the moments of X_t (see [39, 52]): for every $n \geq 0$, every $x \geq 0$, and every $t \geq 0$,

$$\mathbb{E}_x(X_t^n) = \frac{n!}{\prod_{k=1}^n \theta_k} + n! \sum_{m=1}^n \left(\sum_{k=0}^m \frac{x^k}{k!} \prod_{\substack{j=k \\ j \neq m}}^n \frac{1}{\theta_j - \theta_m} \right) e^{-\theta_m t}, \quad (4)$$

where $\theta_n = \lambda(1 - 2^{-n}) = n\lambda_n$ for any $n \geq 1$. Obviously, assuming for example that $x > y$,

$$\begin{aligned} W_n(\delta_x P_t, \delta_y P_t)^n &\geq \mathbb{E}_x((X_t)^n) - \mathbb{E}_y((Y_t)^n) \\ &\underset{t \rightarrow \infty}{\sim} n! \left(\sum_{k=0}^n \frac{x^k - y^k}{k!} \prod_{j=k}^{n-1} \frac{1}{\theta_j - \theta_n} \right) e^{-\theta_n t}. \end{aligned}$$

As a consequence, the rate of convergence in Equation (3) is optimal for any $n \geq 1$.

3.3 Convergence in total variation distance

The estimate for the Wasserstein rate of convergence does not provide on its own any information about the total variation distance between $\delta_x P_t$ and $\delta_y P_t$. It turns out that this rate of convergence is the one of the W_1 distance. This is established in [57, Thm 1.1]. Let us provide here an improvement of this result by a probabilistic argument.

Theorem 3.4 (Convergence in total variation distance). *For any $x, y \geq 0$ and $t \geq 0$,*

$$\|\delta_x P_t - \delta_y P_t\|_{TV} \leq \lambda e^{-\lambda t/2} |x - y| + e^{-\lambda t}. \quad (5)$$

As a consequence, for any measure ν with a finite first moment and $t \geq 0$,

$$\|\nu P_t - \mu\|_{TV} \leq \lambda e^{-\lambda t/2} W_1(\nu, \mu) + e^{-\lambda t} \|\nu - \mu\|_{TV}. \quad (6)$$

Remark 3.5 (Propagation of the atom). *Note that the upper bound obtained in Equation (5) does not go to zero as $y \rightarrow x$. This is due to the fact that $\delta_x P_t$ has an atom at $y + t$ with mass $e^{-\lambda t}$.*

Proof of Theorem 3.4. The coupling is a slight modification of the Wasserstein one. The paths of $(X_s)_{0 \leq s \leq t}$ and $(Y_s)_{0 \leq s \leq t}$ starting respectively from x and y are determined by their jump times $(T_n^X)_{n \geq 0}$ and $(T_n^Y)_{n \geq 0}$ up to time t . These sequences have the same distribution than the jump times of a Poisson process with intensity λ .

Let $(N_t)_{t \geq 0}$ be a Poisson process with intensity λ and $(T_n)_{n \geq 0}$ its jump times with the convention $T_0 = 0$. Let us now construct the jump times of X and Y . Both processes make exactly N_t jumps before time t . If $N_t = 0$, then

$$X_s = x + s \quad \text{and} \quad Y_s = y + s \quad \text{for } 0 \leq s \leq t.$$

Assume now that $N_t \geq 1$. The $N_t - 1$ first jump times of X and Y are the ones of $(N_t)_{t \geq 0}$:

$$T_k^X = T_k^Y = T_k \quad 0 \leq k \leq N_t - 1.$$

In other words, the Wasserstein coupling acts until the penultimate jump time T_{N_t-1} . At that time, we have

$$X_{T_{N_t-1}} - Y_{T_{N_t-1}} = \frac{x - y}{2^{N_t-1}}.$$

Then we have to define the last jump time for each process. If they are such that

$$T_{N_t}^X = T_{N_t}^Y + X_{T_{N_t-1}} - Y_{T_{N_t-1}},$$

then the paths of X and Y are equal on the interval $(T_{N_t}^X, t)$ and can be chosen to be equal for any time larger than t .

Recall that conditionally on the event $\{N_t = 1\}$, the law of T_1 is the uniform distribution on $(0, t)$. More generally, if $n \geq 2$, conditionally on the set $\{N_t = n\}$, the law of the penultimate jump time T_{n-1} has a density $s \mapsto n(n-1)t^{-n}(t-s)s^{n-2}\mathbb{1}_{(0,t)}(s)$ and conditionally on the event $\{N_t = n, T_{n-1} = s\}$, the law of T_n is uniform on the interval (s, t) .

Conditionally on $N_t = n \geq 1$ and T_{n-1} , T_n^X and T_n^Y are uniformly distributed on (T_{n-1}, t) and can be chosen such that

$$\begin{aligned} \mathbb{P}\left(T_n^X = T_n^Y + \frac{x-y}{2^{n-1}} \mid N_t^X = N_t^Y = n, T_{n-1}^X = T_{n-1}^Y = T_{n-1}\right) \\ = \left(1 - \frac{|x-y|}{2^{n-1}(t-T_{n-1})}\right) \vee 0 \geq 1 - \frac{|x-y|}{2^{n-1}(t-T_{n-1})}. \end{aligned}$$

This coupling provides that

$$\begin{aligned} \|\delta_x P_t - \delta_y P_t\|_{\text{TV}} &\leq 1 - \mathbb{E}\left[\left(1 - \frac{|x-y|}{2^{N_t-1}(t-T_{N_t-1})}\right) \mathbb{1}_{\{N_t \geq 1\}}\right] \\ &\leq e^{-\lambda t} + |x-y| \mathbb{E}\left[\frac{2^{-N_t+1}}{(t-T_{N_t-1})} \mathbb{1}_{\{N_t \geq 1\}}\right]. \end{aligned}$$

For any $n \geq 2$,

$$\mathbb{E}\left(\frac{1}{t-T_{N_t-1}} \mid N_t = n\right) = \frac{n(n-1)}{t^n} \int_0^t u^{n-2} du = \frac{n}{t}.$$

This equality also holds for $n = 1$. Thus we get that

$$\mathbb{E}\left(\frac{2^{-N_t+1}}{(t-T_{N_t-1})} \mathbb{1}_{\{N_t \geq 1\}}\right) = \frac{1}{t} \mathbb{E}(N_t 2^{-N_t+1}) = \lambda e^{-\lambda t/2},$$

since N_t is distributed according to the Poisson law with parameter λt . This provides the estimate (5). The general case (6) is a straightforward consequence: if N_t is equal to 0, a coupling in total variation of the initial measures is done, otherwise, we use the coupling above. \square

3.4 Some generalizations

This process on \mathbb{R}_+ belongs to the subclass of the AIMD (Additive Increase Multiplicative Decrease) processes. Its infinitesimal generator is given by

$$Lf(x) = f'(x) + \lambda(x) \int_0^1 (f(ux) - f(x)) \nu(du), \quad (7)$$

where ν is a probability measure on $[0, 1]$ and λ is a non negative function. It can be viewed as the limit behavior of the congestion of a single channel (see [24, 31] for a rigorous derivation of this limit). In [44], the authors give a generalization of the scaling procedure to interpret various PDMPs as the limit of discrete time Markov chains and in [40] more general increase and decrease profiles are considered as models for TCP. In the real world (Internet), the AIMD mechanism allows a good compromise between the minimization of network congestion time and the maximization of mean throughput. See also [12] for a simplified TCP windows size model. See [40, 43, 52, 53, 54, 51, 33] for other works dedicated to this process. Generalization to interacting multi-class transmissions are considered in [29, 30].

Such processes are also used to model the evolution of the size of bacteria or polymers which mixes growth and fragmentation: they growth in a deterministic way with a growth speed $x \mapsto \tau(x)$, and split at rate $x \mapsto \lambda(x)$ into two (for simplicity) parts y and $x - y$ according a kernel $\beta(x, y)dy$. The infinitesimal generator associated to this dynamics writes

$$Lf(x) = \tau(x)f'(x) + \lambda(x) \int_0^x (f(y) - f(x))\beta(x, y) dy.$$

If the initial distribution of the size has a density $u(\cdot, 0)$ then this density is solution of the following integro-differential PDE:

$$\partial_t u(x, t) = -\partial_x(\tau(x)u(x, t)) - \lambda(x)u(x, t) + \int_x^\infty \lambda(y)\beta(y, x)u(y, t) dy.$$

If one is interesting in the density of particles with size x at time t in the growing population (a splitting creates two particles), one has to consider the PDE

$$\partial_t u(x, t) = -\partial_x(\tau(x)u(x, t)) - \lambda(x)u(x, t) + 2 \int_x^\infty \lambda(y)\beta(y, x)u(y, t) dy.$$

This growth-fragmentation equations have been extensively studied from a PDE point of view (see for example [56, 23, 15, 46]). A probabilistic approach is used in [10] to study the pure fragmentation process.

4 Switched flows and motivating examples

Let E be the set $\{1, 2, \dots, n\}$, $(\lambda(\cdot, i, j))_{i, j \in E}$ be nonnegative continuous functions on \mathbb{R}^d , and, for any $i \in E$, $F^i(\cdot) : \mathbb{R}^d \mapsto \mathbb{R}^d$ be a smooth vector field such that the ordinary differential equation

$$\begin{cases} \dot{x}_t = F^i(x_t) & \text{for } t > 0, \\ x_0 = x \end{cases}$$

has a unique and global solution $t \mapsto \varphi_t^i(x)$ on $[0, +\infty)$ for any initial condition $x \in \mathbb{R}^d$. Let us consider the Markov process

$$(Z_t)_{t \geq 0} = ((X_t, I_t))_{t \geq 0} \text{ on } \mathbb{R}^d \times E$$

defined by its infinitesimal generator L as follows:

$$Lf(x, i) = F^i(x) \cdot \nabla_x f(x, i) + \sum_{j \in E} \lambda(x, i, j)(f(x, j) - f(x, i))$$

for any smooth function $f : \mathbb{R}^d \times E \rightarrow \mathbb{R}$.

These PDMP are also known as hybrid systems. They have been intensively studied during the past decades (see for example the review [64]). In particular, they naturally appear as the approximation of Markov chains mixing slow and fast dynamics (see [19]). They could also be seen as a continuous time version of iterated random functions (see the excellent review [22]).

In this section, we present few examples from several applied areas and describe their long time behavior.

4.1 A surprising blow up for switched ODEs

The main probabilistic results of this section are established in [38]. Consider the Markov process (X, I) on $\mathbb{R}^2 \times \{0, 1\}$ driven by the following infinitesimal generator:

$$Lf(x, i) = (A_i x) \cdot \nabla_x f(x, i) + r(f(x, 1 - i) - f(x, i)) \quad (8)$$

where $r > 0$ and A_0 and A_1 are the two following matrices

$$A_0 = \begin{pmatrix} -\alpha & 1 \\ 0 & -\alpha \end{pmatrix} \quad \text{and} \quad A_1 = \begin{pmatrix} -\alpha & 0 \\ -1 & -\alpha \end{pmatrix} \quad (9)$$

for some positive α . In other words, $(I_t)_{t \geq 0}$ is a Markov process on $\{0, 1\}$ with constant jump rate r (from 0 to 1 and from 1 to 0) and $(X_t)_{t \geq 0}$ is the solution of $\dot{X}_t = A_{I_t} X_t$.

The two matrices A_0 and A_1 are Hurwitz matrices (all eigenvalues have strictly negative real parts). Moreover, it is also the case for the matrix $A_p = pA_1 + (1 - p)A_0$ with $p \in [0, 1]$ since the eigenvalues of A_p are $-\alpha \pm i\sqrt{p(1-p)}$. Then, for any $p \in [0, 1]$, there exists $K_p \geq 1$ and $\rho > 0$ such that

$$\|x_t\| \leq K_p \|x_0\| e^{-\rho t},$$

for any solution $(x_t)_{t \geq 0}$ of $\dot{x}_t = A_p x_t$.

4.1.1 Asymptotic behavior of the continuous component

The first step is to use polar coordinates to study the large time behavior of $R_t = \|X_t\|$ and U_t the point on the unit circle S^1 given by X_t/R_t . One gets that

$$\begin{aligned} \dot{R}_t &= R_t \langle A_{I_t} U_t, U_t \rangle \\ \dot{U}_t &= A_{I_t} U_t - \langle A_{I_t} U_t, U_t \rangle U_t. \end{aligned}$$

As a consequence, (U_t, I_t) is a Markov process on $S^1 \times \{0, 1\}$. One can show that it admits a unique invariant measure μ . Therefore, if $\mathbb{P}(R_0 = 0) = 0$,

$$\frac{1}{t} \log R_t = \frac{1}{t} \log R_0 + \frac{1}{t} \int_0^t \langle A_{I_s} U_s, U_s \rangle ds \xrightarrow[t \rightarrow \infty]{a.s.} \int \langle A_i u, u \rangle \mu(du, i).$$

The stability of the Markov process depends on the sign of

$$L(\alpha, r) := \int \langle A_i u, u \rangle \mu(du, i).$$

An "explicit" formula for $L(\alpha, r)$ can be formulated in terms of the classical trigonometric functions

$$\cot(x) = \frac{\cos(x)}{\sin(x)}, \quad \sec(x) = \frac{1}{\cos(x)} \quad \text{and} \quad \csc(x) = \frac{1}{\sin(x)}.$$

Theorem 4.1 (Lyapunov exponent [38]). *For any $r > 0$ and $\alpha > 0$,*

$$L(\alpha, r) = G(r) - \alpha \quad \text{where} \quad G(r) = \int_0^{2\pi} (p_0(\theta; r) - p_1(\theta; r)) \cos(\theta) \sin(\theta) d\theta > 0$$

and p_0 and p_1 are defined as follows: for $\theta \in (-\pi/2, 0)$

$$\begin{aligned} H(\theta; r) &= \exp(-2r \cot(2\theta)) \int_{\theta}^0 \exp(2r \cot(2y)) \sec^2(y) dy, \\ C(r) &= \left[4 \int_{-\pi/2}^0 \sec^2(x) + (\csc^2(x) - \sec^2(x)) r H(x; r) dx \right]^{-1}, \\ p_0(\theta; r) &= C(r) \csc^2(\theta) r H(\theta; r), \\ p_1(\theta; r) &= C(r) \sec^2(\theta) [1 - r H(\theta; r)], \end{aligned}$$

and for any $\theta \in \mathbb{R}$,

$$p_i(\theta; r) = p_{1-i}(\theta + \pi/2; r) = p_i(\theta + \pi; r).$$

Sketch of proof of Theorem 4.1. Let us denote by $(\Theta_t)_{t \geq 0}$ the lift of $(U_t)_{t \geq 0}$. The process (Θ, I) is also Markovian. Moreover, its infinitesimal generator is given by

$$\mathcal{L}f(\theta, i) = -[i \cos^2(\theta) + (1-i) \sin^2(\theta)] \partial_{\theta} f(\theta, i) + r[f(\theta, 1-i) - f(\theta, i)].$$

Notice that the dynamics of (Θ, I) does not depend on the parameter α . This process has a unique invariant measure μ (depending on the jump rate r). With the one-to-one correspondence between a point on S^1 and a point in $[0, 2\pi)$, let us write the invariant probability measure μ as

$$\mu(d\theta, i) = p_i(\theta; r) \mathbf{1}_{[0, 2\pi)}(\theta) d\theta,$$

The functions p_0 and p_1 are solution of

$$\begin{cases} \partial_{\theta}(\sin^2(\theta) p_0(\theta)) + r(p_1(\theta) - p_0(\theta)) = 0, \\ \partial_{\theta}(\cos^2(\theta) p_1(\theta)) + r(p_0(\theta) - p_1(\theta)) = 0. \end{cases}$$

These relations provide the desired expressions. \square

The previous technical result provides immediately the following result on the (in)stability of the process.

Corollary 4.2 ((In)Stability [38]). *There exist $\alpha > 0$, $a > 0$ and $b > 0$ such that $L(\alpha, r)$ is negative if $r < a$ or $r > b$ and $L(\alpha, r)$ is positive for some $r \in (a, b)$.*

From numerical experiments, see Figure 1, one can formulate the following conjecture on the function G .

Conjecture 4.3 (Shape of G). *There exists $r_c \sim 4.6$ such that $G'(r) > 0$ for $r < r_c$ and $G'(r) < 0$ for $r > r_c$ and $G(r_c) \sim 0.2$. Moreover,*

$$\lim_{r \rightarrow 0} G(r) = 0 \quad \text{and} \quad \lim_{r \rightarrow \infty} G(r) = 0.$$

Open question 2 (Shape of the instability domain). *Is it possible to prove Conjecture 4.3? This would imply that the set*

$$U_{\alpha} = \left\{ r > 0 : \|X_t\| \xrightarrow[t \rightarrow \infty]{p.s.} +\infty \right\} = \{r > 0 : L(r, \alpha) > 0\} = \{r > 0 : G(r) > \alpha\}$$

is empty for $\alpha > G(r_c)$ and is a non empty interval if $\alpha < G(r_c)$.

Remark 4.4 (On the irreducibility of (U, I)). *Notice that one can modify the matrices A_0 and A_1 in such a way that (U, I) has two ergodic invariant measures (see [9]).*

Open question 3 (Oscillations of the Lyapunov exponent). *Is it possible to choose the two 2×2 matrices A_0 and A_1 in such a way that the set of jump rates r associated to unstable processes is the union of several intervals?*

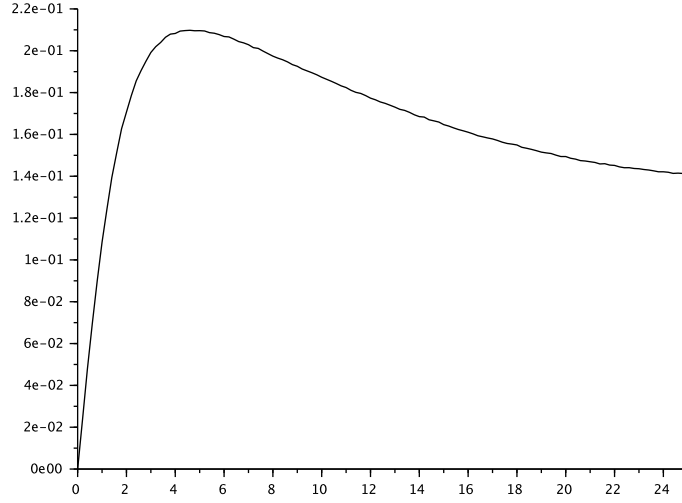


Figure 1: Shape of the function G defined in Theorem 4.1.

4.1.2 A deterministic counterpart

Consider the following ODE

$$\dot{x}_t = (1 - u_t)A_0x_t + u_tA_1x_t, \quad (10)$$

where u is a given measurable function from $[0, \infty)$ to $\{0, 1\}$. The system is said to be *unstable* if there exists a starting point x_0 and a measurable function $u : [0, \infty) \rightarrow \{0, 1\}$ such that the solution of (10) goes to infinity.

In [13, 4, 5], the authors provide necessary and sufficient conditions for the solution of (10) to be unbounded for two matrices A_0 and A_1 in $\mathcal{M}_2(\mathbb{R})$. In the particular case (9), this result reads as follows.

Theorem 4.5 (Criterion for stability [5]). *If A_0 and A_1 are given by (9), the system (10) is unbounded if and only if*

$$R(\alpha^2) := \frac{1 + 2\alpha^2 + \sqrt{1 + 4\alpha^2}}{2\alpha^2} e^{-2\sqrt{1+4\alpha^2}} > 1. \quad (11)$$

More precisely, the result in [5] ensures that

- if $2\alpha > 1$ (case S1 in [5]) then there exists a common quadratic Lyapunov function for A_0 and A_1 (and $\|X_t\|$ goes to 0 exponentially fast as $t \rightarrow \infty$ for any function u),
- if $2\alpha \leq 1$ (case S4 in [5]) then, the system is
 - globally uniformly asymptotically stable (and $\|X_t\|$ goes to 0 exponentially fast as $t \rightarrow \infty$ for any function u) if $R(\alpha^2) < 1$,
 - uniformly stable (but for some functions u , $\|X_t\|$ does not converge to 0) if $R(\alpha^2) = 1$,
 - unbounded if $R(\alpha^2) > 1$,

where $R(\alpha^2)$ is given by (11).

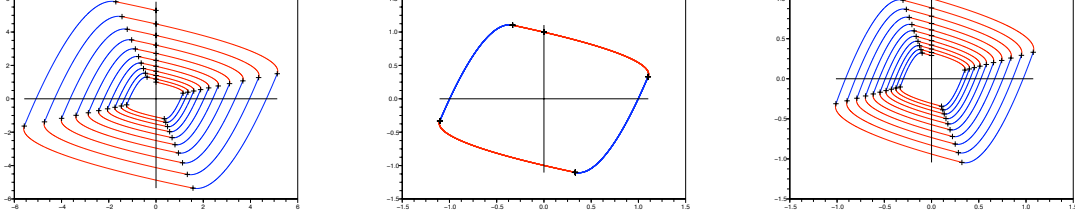


Figure 2: The *worth trajectory* with $\alpha = 0.32$ (on the left), $\alpha = 0.3314$ (in the middle) and $\alpha = 0.34$ (on the right). The system evolves clock-wisely from $(0, 1)$.

Proof of Theorem 4.5. The general case is considered in [5]. The main idea is to construct the so-called *worst trajectory* choosing at each instant of time the vector field that drives the particle away from the origin. The solutions $x_t = (y_t, z_t)$ of $\dot{x}_t = A_0 x_t$ and $\dot{x}_t = A_1 x_t$ starting from $x_0 = (y_0, z_0)$ are respectively given by

$$\begin{cases} y_t = (z_0 t + y_0)e^{-\alpha t} \\ z_t = z_0 e^{-\alpha t} \end{cases} \quad \text{and} \quad \begin{cases} y_t = y_0 e^{-\alpha t} \\ z_t = (-y_0 t + z_0)e^{-\alpha t}. \end{cases}$$

Let us define, for $x = (y, z)$,

$$Q(x) = \det(A_0 x, A_1 x) = \alpha y^2 - yz - \alpha z^2.$$

Then the set of the points where $A_0 x$ and $A_1 x$ are collinear is given by

$$\{x \in \mathbb{R}^2 : Q(x) = 0\} = \{x = (y, z) : y = \gamma^+ z \text{ or } y = \gamma^- z\}$$

where

$$\gamma^+ = \frac{1 + \sqrt{1 + 4\alpha^2}}{2\alpha} > 0 \quad \text{and} \quad \gamma^- = \frac{1 - \sqrt{1 + 4\alpha^2}}{2\alpha} < 0.$$

Let us start with $x_0 = (0, 1)$ and $I_0 = 0$. Choose $t_1 = \gamma^+$ in such a way that:

$$x_{t_1} = (\gamma^+ e^{-\alpha \gamma^+}, e^{-\alpha \gamma^+}).$$

Now, set $t_2 = t_1 + \gamma^+ - \gamma^-$ and $I_t = 1$ for $t \in [t_1, t_2]$ in such a way that $y_{t_2} = \gamma^- z_{t_2}$ i.e. $y_{t_2} = -(\gamma^+)^{-1} z_{t_2}$. Then, one has

$$x_{t_2} = (\gamma^+ e^{-\alpha(2\gamma^+ - \gamma^-)}, -(\gamma^+)^2 e^{-\alpha(2\gamma^+ - \gamma^-)}).$$

Finally, choose $t_3 = t_2 - \gamma^-$ and $I_t = 0$ for $t \in [t_2, t_3]$ in such a way that $y_{t_3} = 0$. Then, one has

$$x_{t_3} = (0, -(\gamma^+)^2 e^{-2\alpha(\gamma^+ - \gamma^-)}).$$

The process is unbounded if and only if $\|x_{t_3}\| > 1$. This is equivalent to (11). \square

4.2 Invariant measure(s) of switched flows

In order to avoid the possible explosions studied in Section 4.1, one can impose that the state space of the continuous variable is a compact set.

In [7], it is shown thanks to an example that the number of the invariant measures may depend on the jump rate for fixed vector fields (as for the problem of (un)-stability described in the previous section). Moreover Hörmander-like conditions on the vector fields are formulated in [2, 7] to ensure that the first marginal of the invariant measure(s) may be absolutely continuous with respect to the Lebesgue measure on \mathbb{R}^d . However the density may blow up as it is shown in the example below.

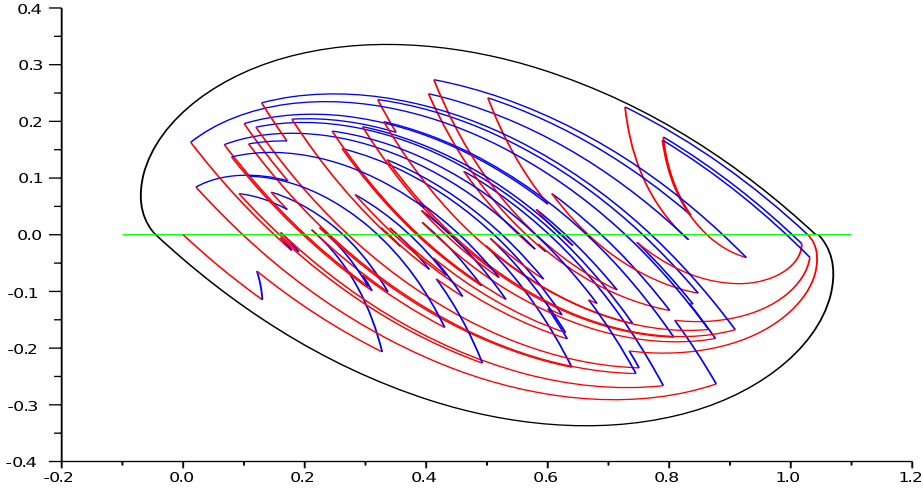


Figure 3: Path of the process associated to F^0 and F^1 given by (12) starting from the origin. Red (resp. blue) pieces of path correspond to $I = 1$ (resp. $I = 0$).

Example 4.6 (Possible blow up of the density near a critical point). *Consider the process on $\mathbb{R} \times \{0, 1\}$ associated to the infinitesimal generator*

$$Lf(x, i) = -\alpha_i(x - i)\partial_x f(x, i) + \lambda_i(f(x, 1 - i) - f(x, i)).$$

This process is studied in [36, 58]. The support of its invariant measure μ is the set $[0, 1] \times \{0, 1\}$ and μ is given by

$$\int f d\mu = \frac{\lambda_1}{\lambda_0 + \lambda_1} \int_0^1 f(x, 0) p_0(x) dx + \frac{\lambda_0}{\lambda_0 + \lambda_1} \int_0^1 f(x, 1) p_1(x) dx,$$

where p_0 and p_1 are Beta distributions:

$$p_0(x) = \frac{x^{\lambda_0/\alpha_0 - 1} (1 - x)^{\lambda_1/\alpha_1}}{B(\lambda_0/\alpha_0, \lambda_1/\alpha_1 + 1)} \quad \text{and} \quad p_1(x) = \frac{x^{\lambda_0/\alpha_0} (1 - x)^{\lambda_1/\alpha_1 - 1}}{B(\lambda_0/\alpha_0 + 1, \lambda_1/\alpha_1)}.$$

The density of the invariant measure possibly explodes near 0 or 1.

The paper [3] is a detailed analysis of invariant measures for switched flows in dimension one. In particular, the authors prove smoothness of the invariant densities away from critical points and describe the asymptotics of the invariant densities at critical points.

The situation is more intricate for higher dimensions.

Example 4.7 (Possible blow up of the density in the interior of the support). *Consider the process on $\mathbb{R}^2 \times \{0, 1\}$ associated to the constant jump rates λ_0 and λ_1 for the discrete component and the vector fields*

$$F^0(x) = Ax \text{ and } F^1(x) = A(x - a) \text{ where } A = \begin{pmatrix} -1 & -1 \\ 1 & -1 \end{pmatrix} \quad \text{and} \quad a = \begin{pmatrix} 1 \\ 0 \end{pmatrix}. \quad (12)$$

The origin and a are the respective unique critical points of F^0 and F^1 . Thanks to the precise estimates in [3], one can prove the following fact. If λ_0 is small enough then, as for one-dimensional example, the density of the invariant measure blows up at the origin. This also implies that the density is infinite on the set $\{\varphi_t^1(0) : t \geq 0\}$.

Open question 4. *What can be said on the smoothness of the density of the invariant measure of such processes?*

4.3 A convergence result

This section sums up the study of the long time behavior of certain switched flows presented in [8]. See also [61] for another approach. To focus on the main lines of this paper, the hypotheses below are far from the optimal ones.

Hypothesis 4.8 (Regularity of the jump rates). *There exist $\underline{a} > 0$ and $\kappa > 0$ such that, for any $x, \tilde{x} \in \mathbb{R}^d$ and $i, j \in E$,*

$$a(x, i, j) \geq \underline{a} \quad \text{and} \quad \sum_{j \in E} |a(x, i, j) - a(\tilde{x}, i, j)| \leq \kappa \|x - \tilde{x}\|.$$

The lower bound condition insures that the second — discrete — coordinate of Z changes often enough (so that the second coordinates of two independent copies of Z coincide sufficiently often).

Hypothesis 4.9 (Strong dissipativity of the vector fields). *There exists $\alpha > 0$ such that,*

$$\langle x - \tilde{x}, F^i(x) - F^i(\tilde{x}) \rangle \leq -\alpha \|x - \tilde{x}\|^2, \quad x, \tilde{x} \in \mathbb{R}^d, \quad i \in E. \quad (13)$$

Hypothesis 4.9 ensures that, for any $i \in E$,

$$\|\varphi_t^i(x) - \varphi_t^i(\tilde{x})\| \leq e^{-\alpha t} \|x - \tilde{x}\|, \quad x, \tilde{x} \in \mathbb{R}^d.$$

As a consequence, the vector fields F^i has exactly one critical point $\sigma(i) \in \mathbb{R}^d$. Moreover it is exponentially stable since, for any $x \in \mathbb{R}^d$,

$$\|\varphi_t^i(x) - \sigma(i)\| \leq e^{-\alpha t} \|x - \sigma(i)\|.$$

In particular, X cannot escape from a sufficiently large ball $\bar{B}(0, M)$. Define the following distance \mathcal{W}_1 on the probability measures on $B(0, M) \times E$: for $\eta, \tilde{\eta} \in \mathcal{P}(B(0, M) \times E)$,

$$\mathcal{W}_1(\eta, \tilde{\eta}) = \inf \left\{ \mathbb{E}|X - \tilde{X}| + \mathbb{P}(I \neq \tilde{I}) : (X, I) \sim \eta \text{ and } (\tilde{X}, \tilde{I}) \sim \tilde{\eta} \right\}.$$

Theorem 4.10 (Long time behavior [8]). *Assume that Hypotheses 4.8 and 4.9 hold.*

Then, the process has a unique invariant measure and its support is included in $\bar{B}(0, M) \times E$. Moreover, let ν_0 and $\tilde{\nu}_0$ be two probability measures on $\bar{B}(0, M) \times E$. Denote by ν_t the law of Z_t when Z_0 is distributed as ν_0 . Then there exist positive constants c and γ such that

$$\mathcal{W}_1(\eta_t, \tilde{\eta}_t) \leq ce^{-\gamma t}.$$

The constants c and γ can be explicitly expressed in term of the parameters of the model (see [8]). The proof relies on the construction of an explicit coupling. See also [17, 48].

Open question 5. *One can apply Theorem 4.10 to the processes defined in Examples 4.6 and 4.7. The associated time reversal processes are associated to unstable vector fields and unbounded jump rates. What can be said about their convergence to equilibrium?*

Section 4.4 present an application of this theorem to a biological model. In Section 4.5, we describe a naïve model for the movement of bacteria that can also be seen as an ergodic telegraph process.

4.4 Neuron activity

The paper [55] establishes limit theorems for a class of stochastic hybrid systems (continuous deterministic dynamic coupled with jump Markov processes) in the fluid limit (small jumps at high frequency), thus extending known results for jump Markov processes. The main results are a functional law of large numbers with exponential convergence speed, a diffusion approximation, and a functional central limit theorem. These results are then applied to neuron models with stochastic ion channels, as the number of channels goes to infinity, estimating the convergence to the deterministic model. In terms of neural coding, the central limit theorems allows to estimate numerically the impact of channel noise both on frequency and spike timing coding.

The Morris–Lecar model introduced in [49] describes the evolution in time of the electric potential $V(t)$ in a neuron. The neuron exchanges different ions with its environment via ion channels which may be open or closed. In the original – deterministic – model, the proportion of open channels of different types are coded by two functions $m(t)$ and $n(t)$, and the three quantities m , n and V evolve through the flow of an ordinary differential equation.

Various stochastic versions of this model exist. Here we focus on a model described in [63], to which we refer for additional information. This model is motivated by the fact that m and n , being proportions of open channels, are better coded as discrete variables. More precisely, we fix a large integer K (the total number of channels) and define a PDMP (V, u_1, u_2) with values in $\mathbb{R} \times \{0, 1/K, 2/K \dots, 1\}^2$ as follows.

Firstly, the potential V evolves according to

$$\frac{dV(t)}{dt} = \frac{1}{C} \left(I - \sum_{i=1}^3 g_i u_i(t) (V - V_i) \right) \quad (14)$$

where C and I are positive constants (the capacitance and input current), the g_i and V_i are positive constants (representing conductances and equilibrium potentials for different types of ions), $u_3(t)$ is equal to 1 and $u_1(t)$, $u_2(t)$ are the (discrete) proportions of open channels for two types of ions.

These two discrete variables follow birth-death processes on $\{0, 1/K, \dots, 1\}$ with birth rates α_1 , α_2 and death rates β_1 , β_2 that depend on the potential V :

$$\begin{aligned} \alpha_i(V) &= c_i \cosh \left(\frac{V - V'_i}{2V''_i} \right) \left(1 + \tanh \left(\frac{V - V'_i}{V''_i} \right) \right) \\ \beta_i(V) &= c_i \cosh \left(\frac{V - V'_i}{2V''_i} \right) \left(1 - \tanh \left(\frac{V - V'_i}{V''_i} \right) \right) \end{aligned} \quad (15)$$

where the c_i and V'_i , V''_i are constants.

Let us check that Theorem 4.10 can be applied in this example. Formally the process is a PDMP with $d = 1$ and the finite set $E = \{0, 1/K, \dots, 1\}^2$. The discrete process (u_1, u_2) plays the role of the index $i \in E$, and the fields $F^{(u_1, u_2)}$ are defined (on \mathbb{R}) by (14) by setting $u_1(t) = u_1$, $u_2(t) = u_2$.

The constant term $u_3 g_3$ in (14) ensures that the uniform dissipation property (13) is satisfied: for all (u_1, u_2) ,

$$\begin{aligned} \langle V - \tilde{V}, F^{(u_1, u_2)}(V) - F^{(u_1, u_2)}(\tilde{V}) \rangle &= -\frac{1}{C} \sum_{i=1}^3 u_i g_i (V - \tilde{V})^2 \\ &\leq -\frac{1}{C} u_3 g_3 (V - \tilde{V})^2. \end{aligned}$$

The Lipschitz character and the bound from below on the rates are not immediate. Indeed the jump rates (15) are not bounded from below if V is allowed to take values in \mathbb{R} .

However, a direct analysis of (14) shows that V is essentially bounded : all the fields $F^{(u_1, u_2)}$ point inward at the boundary of the (fixed) line segment $\mathcal{S} = [0, \max(V_1, V_2, V_3 + (I + 1)/g_3 u_3)]$, so if $V(t)$ starts in this region it cannot get out. The necessary bounds all follow by compactness, since $\alpha_i(V)$ and $\beta_i(V)$ are \mathcal{C}^1 in \mathcal{S} and strictly positive.

4.5 Chemotaxis

Let us briefly describe how bacteria move (see [50, 26, 25] for details). They alternate two basic behavioral modes: a more or less linear motion, called a run, and a highly erratic motion, called tumbling, the purpose of which is to reorient the cell. During a run the bacteria move at approximately constant speed in the most recently chosen direction. Run times are typically much longer than the time spent tumbling. In practice, the tumbling time is neglected. An appropriate stochastic process for describing the motion of cells is called the *velocity jump process* which is deeply studied in [50]. The velocity belongs to a compact set (the unit sphere for example) and changes by random jumps at random instants of time. Then, the position is deduced by integration of the velocity. The jump rates may depend on the position when the medium is not homogeneous: when bacteria move in a favorable direction *i.e.* either in the direction of foodstuffs or away from harmful substances the run times are increased further. Sometimes, a diffusive approximation is available [50, 60].

In the one-dimensional simple model studied in [27], the particle evolves in \mathbb{R} and its velocity belongs to $\{-1, +1\}$. Its infinitesimal generator is given by:

$$Af(x, v) = v\partial_x f(x, v) + \left(a + (b - a)\mathbb{1}_{\{xv > 0\}}\right)(f(x, -v) - f(x, v)), \quad (16)$$

with $0 < a < b$. The dynamics of the process is simple: when X goes away from 0, (resp. goes to 0), V flips to $-V$ with rate b (resp. a). Since $b > a$, it is quite intuitive that this Markov process is ergodic. One could think about it as an analogue of the diffusion process solution of

$$dZ_t = dB_t - \text{sign}(Z_t) dt.$$

More precisely, under a suitable scaling, one can show that X goes to Z . Finally, this process is an ergodic version of the so-called telegraph process. See for example [35, 32].

Of course, this process does not satisfy the hypotheses of Theorem 4.10 since the vector fields have no stable point. It is shown in [27] that the invariant measure μ of (X, V) driven by (16) is the product measure on $\mathbb{R}_+ \times \{-1, +1\}$ given by

$$\mu(dx, dv) = (b - a)e^{-(b-a)x} dx \otimes \frac{1}{2}(\delta_{-1} + \delta_{+1})(dv).$$

One can also construct an explicit coupling to get explicit bounds for the convergence to the invariant measure in total variation norm [27]. See also [47] for another approach, linked with functional inequalities.

Open question 6 (More realistic models). *Is it possible to establish quantitative estimates for the convergence to equilibrium for more realistic dynamics (especially in \mathbb{R}^3) as considered in [50, 26, 25]?*

Acknowledgements. FM deeply thanks Persi Diaconis for his energy, curiosity and enthusiasm and Laurent Miclo for the perfect organisation of the stimulating workshop "Talking Across Fields" in Toulouse during March 2014. This paper has been improved thanks to the constructive comments of two referees. FM acknowledges financial support from the French ANR project ANR-12-JS01-0006 - PIECE.

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